## TopWorx ${ }^{\text {TM }}$ TV-Series Valve Controllers

Installation, Operation \& Maintenance Manual


## Emerson ${ }^{\text {TM }}$

Emerson is a powerful, global, single source of process improvement technology and expertise. We help major companies in selected industries optimize their plants and processes to achieve higher quality, greater reliability and faster time to market, while steadily advancing productivity and profitability.

Emerson's technology know-how and application experience enable us to develop products and solutions that deliver the proven performance and reliability our customers expect when looking to build, connect, improve, and maintain their equipment and automation process.

## DrivenWithoutCompromise

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## Installation on Actuator

## Normal and Reverse Acting

Normal acting is full clockwise (CW) when the process valve is closed and counterclockwise (CCW) when the process valve is open. Reverse acting is full CW when the process valve is open and CCW when the process valve is closed.

Indicator dome assemblies are designed to accommodate both Normal and Reverse Acting units. When the unit is Reverse Acting, the indicator dome assembly will have to be rotated.

The image to the right shows a TopWorx ${ }^{\top M}$ unit mounted parallel to the process valve in the closed position. The green arrow at the top shows the "normal acting" direction of travel to open the valve. This is the standard orientation of your unit unless otherwise specified and will be factory set to operate in this fashion.

## Installation on Actuator Mounting

TopWorx ${ }^{T M}$ has numerous mounting bracket kits available to meet your specific application, whether rotary or linear. Consult your local distributor or factory representative for ordering information. The illustration shows a direct Namur mount on a quarter turn valve. Refer to your mounting kit documentation for specific mounting instructions.

## Installation Notes

1. Remove the upper housing of the unit to allow access to the target cam assembly.
2. Hold the unit above the mounting surface in the orientation in which you intend to mount. Rotate the shaft to align the tang with the actuator slot. In some cases, it may be necessary to rotate the target cam on the shaft to allow assembly. For most units the target cam is secured with a compression spring. Simply grasp the cam, push down, and realign the cam as required. On some units the target cam is secured with a snap ring. On these units, removal of the shaft from the base assembly will be required to change the orientation. Once removed from the base assembly, remove the snap ring securing the target cam and rotate as required.
3. Use caution not to allow undue axial (thrust) load on the shaft.
4. Cycle the valve a couple of times prior to final tightening of the mounting kit hardware. This allows the shaft to self-center in the pinion slot, or coupler. Refer to the dimensions and materials section of this document for appropriate tightening torque.
5. Always use sound mechanical practices when torqueing down any hardware or making pneumatic connections. Refer to the Integrated Pneumatic Control Valves section for detailed information on pneumatic connections.
6. This product comes shipped with conduit covers to protect the internal components from debris during shipment and handling. It is the responsibility of the receiving and/or installing personnel to provide appropriate permanent sealing devices to prevent the intrusion of debris, and moisture, when stored outdoors, or when installed.
7. It is the responsibility of the installer, or end user, to install this product in accordance with the National Electrical Code (NFPA 70) or any other national or regional code defining proper practices.



| MATERIALS OF CONSTRUCTION |  |
| :--- | :--- |
| Enclosure | Lexan 123R UV F1 Rated |
| Fasteners | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Indicator Dome | Lexan 123R UV F1 Rated |
| Seals | Nitrile/EPDM/Silicone (Other materials <br> available upon request) |


| Fastener Torque Specifications |  |
| :--- | :--- |
| Enclosure Housing Bolts | $224 \mathrm{in}-\mathrm{oz}[1,582 \mathrm{mN} \cdot \mathrm{m}]+/-10 \%$ |
| Indicator Dome Screws | $200 \mathrm{in}-\mathrm{oz}[141 \mathrm{mN} \cdot \mathrm{m}]$ |
| Mounting Holes | $4 \mathrm{ft}-\mathrm{lbs}[5.4 \mathrm{~N} \cdot \mathrm{~m}]+/-10 \%$ |



## Dimensions and Materials: TopWorxTM TVF (Domed Lid)



## Dimensions and Materials: TopWorx ${ }^{\text {TM }}$ TVL (Domed Lid)



| MATERIALS OF CONSTRUCTION |  |
| :--- | :--- |
| Enclosure | Cast A360 aluminum with dichromate <br> conversion coating inside \& out, epoxy coated <br> exterior rated for 1,000 hrs salt spray per <br> ASTM B117 |
| Fasteners | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft Bushing | ASTM C83600 Bronze |
| Indicator Dome | Lexan 123R, UVF1 rated |
| Seals | Silicone |


| Maximum Fastener Torque Specifications |  |
| :--- | :--- |
| Enclosure Housing Bolts | $8 \mathrm{ft} \mathrm{l} \mathrm{bs}[10.8 \mathrm{~N} \cdot \mathrm{~m}]$ |
| Indicator Dome Screws | $200 \mathrm{in}-\mathrm{oz}[141 \mathrm{mN} \cdot \mathrm{m}]$ |
| Bottom Mounting Holes | $10 \mathrm{ft}-\mathrm{lbs}[13.6 \mathrm{~N} \cdot \mathrm{~m}]$ |



Dimensions and Materials: TopWorx ${ }^{\text {TM }}$ TVH (Domed Lid)


| MATERIALS OF CONSTRUCTION |  |
| :--- | :--- |
| Enclosure | Stainless Steel, 316 |
| Fasteners | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft Bushing | ASTM C83600 Bronze |
| Indicator Dome | Lexan 123R, UVF1 rated |
| Seals | Silicone |


| Maximum Fastener Torque Specifications |  |
| :--- | :--- |
| Enclosure Housing Bolts | 8 ft -lbs $[10.8 \mathrm{~N} \cdot \mathrm{~m}]$ |
| Indicator Dome Screws | $200 \mathrm{in}-0 \mathrm{z}[141 \mathrm{mN} \cdot \mathrm{m}]$ |
| Bottom Mounting Holes | $10 \mathrm{ft}-\mathrm{lbs}[13.6 \mathrm{~N} \cdot \mathrm{~m}]$ |



Dimensions and Materials: TopWorx ${ }^{\text {TM }}$ TVL (Flat Lid)


## Dimensions and Materials: TopWorxTM TVH (Flat Lid)



| MATERIALS OF CONSTRUCTION |  |
| :--- | :--- |
| Enclosure | Cast A360 aluminum with dichromate <br> conversion coating inside \& out, epoxy coated <br> exterior rated for 1,000 hrs salt spray per <br> ASTM B117 |
| Fasteners | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft | 304 Stainless Steel standard <br> 316 Stainless Steel optional |
| Shaft Bushing | ASTM C83600 Bronze |
| Indicator Dome | Lexan 123R, UVF1 rated |
| Seals | Silicone |


| Maximum Fastener Torque Specifications |  |
| :--- | :--- |
| Enclosure Housing Bolts | $8 \mathrm{ft}-\mathrm{lbs}[10.8 \mathrm{~N} \cdot \mathrm{~m}]$ |
| Indicator Dome Screws | $200 \mathrm{in}-0 \mathrm{z}[141 \mathrm{mN} \cdot \mathrm{m}]$ |
| Bottom Mounting Holes | $10 \mathrm{ft}-\mathrm{lbs}[13.6 \mathrm{~N} \cdot \mathrm{~m}]$ |



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Dimensions and Materials: Shaft Detail


Sensors: Basic Function
Each T-Series unit is equipped with 2 or 4 adjustable targets with a usable range between $90^{\circ}$ and $45^{\circ}$. For normal acting applications, the targets are color coded red for closed and green for open. The color code would be reversed for reverse acting units. After installing the unit on the actuator or valve assembly, the targets must be set.

## Normal acting

1. Rotate the valve full CW to the closed position.
2. Twist the red target or press and move the metal target CW or CCW as required to engage the switch (refer to the specific switch section for testing and confirmation information about your switch type).
3. Rotate the valve full CCW to the open position.
4. Twist the green target or press and move the metal target CW or CCW as required to engage the switch (refer to the specific switch section for testing and confirmation information about your switch type).

## Reverse acting

1. Rotate the valve full CW to the open position.
2. Twist the red target or press and move the metal targets CW or CCW as required to engage the switch (refer to the specific switch section for testing and confirmation information about your switch type).
3. Rotate the valve full CCW to the closed position.
4. Twist the green target or press and move the metal target CW or CCW as required to engage the switch (refer to the specific switch section for testing and confirmation information about your switch type).


## Setting Switches

Unlock green and red targets. Stroke the actuator open and closed to ensure there is no obstruction in its stroke. Once actuator is at the desired position, twist the knob on the cam or press and move the metal target until the switch is made and lock the appropriate target. The red knob is for the closed position and the green is for the open position (normal acting).

Warning: Strikers are spring-loaded and may eject forcefully upon disassembly. Use caution when disassembling.

## For switching angle under $45^{\circ}$ (for red and green twist knobs only):

When the switchbox is mounted to a linear actuator, or when the actuator strokes less than $45^{\circ}$, we recommend the following:

1. Remove shaft from switchbox by removing the circlip underneath the switchbox
2. Remove the circlip underneath the cam if equipped, then push the cam down the shaft by $3-4 \mathrm{~mm}$ and turn it $90^{\circ}$
3. Push the cam back up, you will see the flats fit snugly between the locating lugs inside the hub
4. Replace the circlip
5. Remove the closed switch from the bracket and install it on the inside of the bracket next to the open switch

## To re-assemble:

1. Replace the screws with M3 $\times 25 \mathrm{~mm}$ long screws (insert through both switches and bracket and fasten with the nut on the inside closest to the switchbox bearing).

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## To re-assemble (continued):

2. Remove the Closed striker assembly (red) by removing the circlip or screw on top, and install it on the inner rack
3. Unlock and twist the green striker to the other end of the cam's rack. (The red striker assembly should be unlocked and twisted to the other end of the inner rack.)
4. Re-install the shaft in the switchbox and fit the $\mathrm{s} / \mathrm{s}$ washer and circlip to the underside of the switchbox
5. The switches can now be set anywhere between $0^{\circ} \& 45^{\circ}$

For switching angle up to $180^{\circ}$ (for red and green twist knobs only)

1. Remove shaft from switchbox by removing the circlip underneath the switchbox
2. Remove the open switch from the bracket and install it on the inside of the bracket
3. Remove the Open striker assembly (green) by removing the circlip or screw on top, and install it on the inner rack next to the red striker assembly
4. Re-install the shaft in the switchbox and fit the $\mathrm{s} / \mathrm{s}$ washer and circlip to the underside of the switchbox
5. The open switch can now be set anywhere between $90^{\circ}$ \& $180^{\circ}$

## GO ${ }^{\text {TM }}$ Switch Option




LOCKED (aligned)


UN-LOCKED (not aligned)

Target assembly for $90^{\circ}$ rotation

*CAM SHOWN IN CLOSED POSITION

Target assembly for $180^{\circ}$ rotation


EMERSON
Switch Option D2/D4, S2/S4: GO™ Switches

When installing units with $D$ or $S$ switches, a standard voltage ohm meter may be used to set the targets by looking for continuity between the $\mathrm{N} / \mathrm{O}$ and COMMON wires.

## Wiring Diagrams

## SW $1 \& 2$



SW $3 \& 4$


| MATERIALS OF CONSTRUCTION |  |  |
| :--- | :--- | :---: |
| OPTION D |  |  |
| Switch Type | GO™ Switch $^{\|c\|}$ |  |
| Sealed | Sealed Device |  |
| Form | SPDT |  |
| Electrical Rating | 1A@24VDC |  |
|  |  |  |
| Switch Type | GOTM Switch |  |
| Sealed | Hermetically Sealed |  |
| Form | SPDT |  |
| Electrical Rating | $3 m A ~ t o ~ 3 A ~ @ ~ 24 V D C ~ o r ~ 3 A ~$ <br> $@ ~ 120 V A C ~$ |  |
| Terminal Wire Size (D and S) | 2•2.5mm <br> $24 \cdot 14 \mathrm{~A}$ WG |  |

D2/S2 Diagram


D4/S4Diagram


## Specific Conditions of Use:

When the supply to the switches do not exceed $60 \mathrm{VAC} / 85 \mathrm{VDC}$, the supply shall be protected such that transients are limited to a maximum of 119 V .

If the supply is above $60 \mathrm{VAC} / 85 \mathrm{VDC}$, but not exceeding 120 VAC , the supply shall be protected such that the transients are limited to maximum of 138 V .

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## Switch Option M2/M4: SPDT Mechanical Switches

When installing units with M switches, a standard voltage ohm meter may be used to set the target cams by looking for continuity between the N/O and COMMON wires.

## Wiring Diagrams



| PRODUCT SPECIFICATIONS |  |
| :--- | :--- |
| OPTION M |  |
| Switch Type | Mechanical |
| Sealed | No |
| Form | SPDT |
| Terminal Maximum <br> wire size | 4mm squared (14AWG) |
| Electrical Rating | 10A@125VAC or 250VAC |
| Conforming to Standards | UL: 1054 |
| Contact Resistance | 15mI 2 max. (initial) |
| Insulation Resistance | 100M 2 min. (at 500V DC) |
|  | OPTION K |
| Switch Type | Mechanical |
| Sealed | No |
| Form | SPDT |
| Terminal Maximum <br> wire size | 4mm squared (14AWG) |
| Electrical Rating | 0.1A@125VAC MAX |
| Conforming to Standards | UL: 1054 |

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Switch Option T2: DPDT Mechanical Switches

When installing units with T switches, a standard voltage ohm meter may be used to set the target cams by looking for continuity between the N/O and COMMON wires.

## Wiring Diagram



| PRODUCT SPECIFICATIONS |  |
| :--- | :--- |
| Switch Type | Mechanical |
| Sealed | No |
| Form | DPDT |
| Terminal Maximum <br> wire size | $4 \mathrm{~mm}^{2}$ (14AWG) |
| Electrical Rating | 8A 125V AC or 250V AC |
| Conforming to Standards | UL recognized and CSA <br> certified, meets MIL-S-8805 |
| Contact | Silver |



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## Switch Options R2/R4: SPDT Reed Switches

When installing units with $R$ switches, a standard voltage ohm meter may be used to set the target cams by looking for continuity between the N/O and COMMON wires.

## Wiring Diagram



| PRODUCT SPECIFICATIONS |  |
| :--- | :--- |
| OPTION P |  |
| Switching Voltage | DC/AC 120V Max |
| Switching Current | 3 Amp Max |
| Power Rating | $3-100$ Watt |
| Contact Material | Tungsten |
| Form | SPDT |
|  | OPTION R |
| Switching Voltage | DC/AC 30V Max |
| Carry Current | 0.5 Amp Max |
| Switching Current | 0.2 Amp Max |
| Power Rating | 3 Watt |
| Contact Material | Rhodium |
| Form | SPDT |
| Terminal Maximum Wire Size | $4 m^{2}$ (14AWG) |

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## Switch Options P2: SPDT Reed Switches

When installing units with $P$ switches, a standard voltage ohm meter may be used to set the target cams by looking for continuity between the $\mathrm{N} / \mathrm{O}$ and COMMON wires.

## Wiring Diagram



| PRODUCT SPECIFICATIONS |  |
| :--- | :--- |
| OPTION P |  |
| Switching Voltage | DC/AC 120V Max |
| Switching Current | 3 Amp Max |
| Power Rating | $3-100$ Watt |
| Contact Material | Tungsten |
| Form | SPDT |
| OPTION R |  |
| Switching Voltage | DC/AC 30V Max |
| Carry Current | 0.5 Amp Max |
| Switching Current | 0.2 Amp Max |
| Power Rating | 3 Watt |
| Contact Material | Rhodium |
| Form | SPDT |
| Terminal Maximum Wire Size | $4 m m^{2}$ (14AWG) |

## EMERSON

Switch Option DS/RS/PS/MS/KS: TV-LED with SPDT

Proximity Switches

The TV-LED indicator is designed to handle up to two SPDT proximity switch es with LED indication and two pilot valve solenoids. Only the normally open contact of the SPDT proximity switch is utilized in driving the LED circuitry, while the normally closed side may be utilized as a standard dry contact. Terminals S1+, S1-, S2+, and S2- act as a direct feedthrough termination block. Typically, these terminals are utilized to optionally drive either internal or external pilot valve solenoids. However, they may also be used in other applications requiring a feedthrough termination block.

## Wiring Diagram



| PRODUCT SPECIFICATIONS |  |
| :--- | :--- |
| Option DS |  |
| Maximum Operating Voltage | $120 \mathrm{VAC} / 24 \mathrm{VDC}$ |
| Maximum Load Current (IL) | 250 mA |
| Minimum Recommended Load Current | 10 mA |
| Maximum Voltage Drop (IL) | 5 V |
| Options MS/KS |  |
| Maximum Operating Voltage | 120 VAC |
| Maximum Load Current (IL) | 250 mA |
| Minimum Recommended Load Current | 10 mA |
| Maximum Voltage Drop (LL) | 5 V |
|  |  |
| Maximum Operating Voltage | Maximum Load Current (IL) |
| Minimum Recommended Load Current | 120 VAC |
| Maximum Voltage Drop (IL) | 10 mA |
| Option RS |  |
| Maximum Operating Voltage | 5 V |
| Maximum Load Current (IL) | $30 \mathrm{VAC} / 24 \mathrm{VDC}$ |
| Minimum Recommended Load Current | 200 mA |
| Maximum Voltage Drop (IL) | 10 mA |
| Terminal Maximum Wire Size | 5 V |

## MECHANICAL SWITCH



## LED Wiring Diagram



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## Switch Option E2/E4: Inductive NAMUR Sensors

Basic inductive proximity sensors

- 2 mm sensing range
- Flush mountable
- NAMUR output
- Intrinsically safe when connected to an approved switch isolator


## Wiring Diagram: Switch Option E





| PRODUCTSPECIFICATIONS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| General Specifications |  |  | Standard Conformity |  |
| Switching element function |  | NAMUR NC | EMC in accordance with | IEC / EN 60947-5-2:2004 |
| Rated operating distance | sn | 2 mm | Standards | DIN EN 60947-5-6 (NAMUR) |
| Installation |  | embeddable | Ambient Conditions |  |
| Output polarity |  | NAMUR | Ambient temperature | $-25 \ldots 100^{\circ} \mathrm{C}(248 \ldots 373 \mathrm{~K})$ |
| Assured operating distance | sa | 0 ... 1.62 mm | Mechanical Specifications |  |
| Reduction factor rAl |  | 0.25 | Connection type Core cross-section | $130 \mathrm{~mm}, \mathrm{PVC}$ cable 0.14 mm 2 |
| Reduction factor rCu |  | 0.2 | Housing material | PBT |
| Reduction factor rV2A |  | 0.7 | Sensing face | PBT |
| Terminal Maximum Wire Size |  | $4 \mathrm{~mm}^{2}$ (14AWG) |  |  |
| Nominal Ratings |  |  | Protection degree | IP67 |
| Nominal voltage | Uo | 8 V | General Information |  |
| Switching frequency | f | $0 \ldots 1000 \mathrm{~Hz}$ | Use in the hazardous area | see instruction manuals |
| Hysteresis | H | typ. \% | Category | 1G; 2G; 1D |
| Current consumption |  |  | 今 <br> When installing TopWorxTM products with P\&F sensors, we suggest using a commercially available switch tester like P\&F part number: STO-03 switch tester. |  |
| Measuring plate not detected |  | $\geq 3 \mathrm{~mA}$ |  |  |
| Measuring plate detected |  | $\leq 1 \mathrm{~mA}$ |  |  |

Switch Option 42/44 or 52/54: Inductive Sensors

## 42Wiring Diagram



52 Wiring Diagram


| SWITCH OPTION 42 |  |
| :--- | :--- |
| Supply Voltage | $10-30 \mathrm{VDC}$ |
| Load Current (IL) | 100 mA max. |
| Leakage Current (OFFSTATE) | 0.05 mA typ., $0.1 \mathrm{\mu A}$ at $25^{\circ} \mathrm{C}$ |
| Output | PNP normally open |
| Voltage Drop AT IL (MAX.) | $\leq 3 \mathrm{~V}$ |
| Hysteresis | - |
| Short Circuit and <br> Overload Protection | Yes |
| Reverse Polarity | Yes |
| Face Material | PBT |
| Standards | EN $60947-5-2$ |
| Environmental Protection | IP67 |
| Ambient Temperature | $-144^{\circ} \mathrm{F}$ to $+158^{\circ}{ }^{\circ} \mathrm{F}$ |
| $\left(-25.6^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ |  |
| Terminal Maximum Wire Size | $4 \mathrm{~mm}^{2}(14 \mathrm{AWG})$ |


| SWITCH OPTION $\mathbf{5 2}$ |  |
| :--- | :--- |
| Supply Voltage | $5-60 \mathrm{VDC}$ |
| Load Current (IL) | 100 mA max. |
| Leakage Current (Offstate) | 0.05 mA typ., $0.1 \mathrm{\mu A}$ at $25^{\circ} \mathrm{C}$ |
| Output | PNP normally open |
| Voltage Drop AT IL (MAX.) | $\leq 5 \mathrm{VDC}$ |
| Hysteresis | Typ. 0.2 mm |
| Short Circuit and <br> Overload Protection | No |
| Reverse Polarity | Yes |
| Face Material | Crastin |
| Standards | IEC $/ \mathrm{EN} 60947-5-2: 2004$ |
| Environmental Protection | IP67 |
| Ambient Temperature | $-14^{\circ} \mathrm{F}$ to $+185^{\circ} \mathrm{F}$ <br> $\left(-25.6^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ |

Bus Option AM: ASi Protocol with Mechanical SPDT Switches

## Wiring Diagram:



Bus Option AS: ASi Protocol with Reed Switches

## Wiring Diagram:




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Bus Options AM/AS:ASI Protocol

| Openness | $800+$ products, 150 Vendors |
| :---: | :---: |
| Type of Network | Sensor Bus |
| Physical Media | 2-wire cable (flat or round) |
| Network Topology | Bus, Ring, Tree, Star |
| Maximum Devices |  |
| v3.0 | 62 nodes (or $4961 / 0$ points) |
| Maximum Devices |  |
| Maximum Distance | 100 meters |
| Maximum Distance with repeaters (max. of 2 repeaters can be used) | 300 meters |
| Communication Methods |  |
| Transmission Properties | 5 mSec latency max. on fully loaded segment |
| Primary Usage | - Master/Slave with cyclic polling <br> - Manchester Bit Encoding implemented via Alternating Pulse Modulation (APM) |
| Power \& Communications on same pair | - Limited to 200 mA per device power consumption (29.5VDC to 31.6V DC) <br> - Requires AS-i specific power supply on communications bus for de-coding |
| Device Power Supply | - Devices can be supplied frombus (<200 mA) <br> - Additional power can be supplied by AS-i power bus cable having multiple power supplies (required forhigher power outputs) <br> - Supply shall be powered by a limited-voltage power supply |
| Wiring Types |  |
| Round: | Normal 2 wire cable.\#16AWG (1.5mm) |
| Flat: | 2 wire flat AS-i cable (1.5mm conductors) Yellow for communications / Black for additional power |
| Grounding aspects | Ungrounded communications bus |
| Shielding | Unshielded wire |
| Terminators | No terminators required |
| Device Addressing | Automatic when connected one at a time to the segment or with Handheld Addressing Unit |
| Governing Body | ATO (AS-i Trade Organization) |
| Website | www.as-interface.com |
| Electromagnetic Compatibility | EN 61326-1:2006, EN61000-4-2:1995inc. A2:2001,EN61000-4-3:2002, EN61000-4-4:2004 inc. A1:2010, EN 61000-4-6:2009, EN61000-4-8:1993inc. A1:2001, EN 55011:2009 inc. |


| AS-i Bit Settings | Data bit | Bit | Function | Input | Output |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | DO | Input I1 / Output 01 | Closed limit Red | Solenoid switch 1 |
|  |  | D1 | Input 12 / Output 02 | Open limit Green | Solenoid switch 2 |
|  |  | D2 | Input I3 / Output 03 | N/A | Solenoid switch 3 |
|  |  | D3 | Input 4 | Fault Signal (optional) | N/A |
|  | Parameter bit | Bit | Function | Configuration Code |  |
|  |  | P0 | not used | Extended ID code 1 | 7 |
|  |  | P1 | not used | 10 Code | 7 |
|  |  | P2 | not used | Extended ID code 2 | E |
|  |  | P3 | notused | Parameter | 8 |
|  |  | Watchdog | on | ID code | A |

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Bus Option DM/DN: DeviceNet Protocol with Mechanical SPDT Switches

## Wiring Diagram:



Bus Option DN: DeviceNet protocol with Reed Switches

## Wiring Diagram:




## EMERSON

Bus Options DM/DN: DeviceNetProtocol (continued):

Description:
DeviceNet Device Profile:

DeviceNet Conformance:
DeviceNet I/O Protocols: Polled I/O
Change-of-state (COS), Cyclic

Remote multiplexer, compatible with ODVA's DeviceNet protocol for discrete I/O. This is a product family which supports three (3) discrete inputs, two (2) discrete outputs, and 1 analog 10-bit input.

General Purpose Discrete I/O, Class 7 with objects:

- Identity (Class 1)
- Message Router (Class 2)
- DeviceNet (Class 3)
- Assembly (Class 4) --------- 5 instances
- Connection (Class 5)
- Parameter (Class Fhex) ----- 10 instances
- Valve (Class 6E hex )
- Alarm (Class 6F $\mathrm{F}_{\text {hex }}$ ) ---- 5 instances
- Alarm Group (Class 70hex) ---- 2 instances

Designed to conform to the ODVA DeviceNet Specification Volume I, Version 2.0 and Volume II, Version 2.0. Communications: Predefined Master/Slave Connection Set, Group 2 Only Server
//O Electrical Specifications

| Ratings | Min | Typical | Max | Units | Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input Power |  |  |  |  |  |
| Device Power | 11 | 24 | 25 | Vdc | per DeviceNet spec. |
| Discrete Inputs |  |  |  |  |  |
| Inputs | 11 | 24 | 25 | Vdc |  |
| Open, Close Outputs |  |  |  |  |  |
| Max voltage |  |  | 25 | Vdc |  |
| Output current | 0 | 0.02 | 0.5 | A | Each output simultaneously |
| Surge current |  |  | 4 | A peak |  |
| Turn-on time Turn-off time |  | $\begin{aligned} & 10^{*} \\ & 10^{*} \end{aligned}$ | $\begin{aligned} & 40^{* *} \\ & 40^{* *} \end{aligned}$ | $\begin{gathered} \mathrm{m} \\ \mathrm{~s} \end{gathered}$ | *Resistive load <br> **Function of solenoid |

## Standard Conformity

| Electromagnetic Compatibility | EN 61326-1:2006, EN 61000-4-2:2009, EN 61000-4-3:2006 inc. A2:2010, |
| :--- | :--- |
|  | EN 61000-4-4:2004 inc. A1:2010, EN 61000-4-5:2006, EN 61000-4-6:2009, |
|  | EN 61000-4-8:2010, EN 55011:2009 inc. A1:2010, EN 55014-1:2006 |

Module Status (MS)

| LED State | Module Status | Meaning |
| :---: | :---: | :--- |
| OFF | No power | There is no power though DeviceNet. |
| Green | Device operational | Operating normally. |
| Flashing Green | Device in standby | Needs commissioning. |
| Flashing Red | Minor fault | Recoverable fault. |
| Red | Unrecoverable fault | May need replacement. |
| Flashing Red/Green | Device self-testing | In self-test mode. |

Network Status (NS)

| LED State | Module Status | Meaning |
| :---: | :---: | :--- |
| OFF | No power/Not on-line | Has no power or has not completed the <br> Dup_MAC_ID test. |
| Flashing Green | On-line, not connected | on-line but is not allotted to a Master. |
| Green | On-line | Operating normally. |
| Flashing Red | Connection time-out | One or more I/O connections are timed out. |
| Red | Critical link failure | Detected an error which makes it incapable of <br> communicating on the link. (Bus off or Duplicate MAC ID.) |

## EMERSON

Bus Options DM/DN: DeviceNet Protocol (continued):

## How to Install and Establish DeviceNet Communications

1. Make sure that the DeviceNet network is terminated properly.
2. Set the baud rate and address of the device if different from default (see next section on how to address and set baud rate).
3. Make sure that there is power on the DeviceNet network and that it is plugged into a Master device.
4. Connect the DeviceNet wires into the device.
5. In autobaud mode (default), the device Module Status LED (labeled MS) will continue to blink until the device recognizes valid traffic on the DeviceNet link and syncs to a specific baud rate.
6. In fixed baud rate mode, the device will undergo its initialization sequence, flashing both LEDs. After approximately 4 seconds, the Module Status LED (labeled "MS") will go on solid green and the Network LED will flash green.
7. The green Network Status LED (labeled " NS ") will go on solid once the Master recognizes the unit on the link and allocates the connection (commissions it).
8. The device is now operating on the network.

## How to Configure the DeviceNet Node Address and Baud Rate

1. The address and baud rate are pre-set to 63 and 125 k baud at the factory.
2. The user may change these values via dip switch reconfiguration at any time (see the following tables)
3. A change to the baud rate will NOT take effect until the device is reset with either a RESET command or a power cycle.
4. A change to the address will be saved internally and will cause the unit to immediately undergo a soft reset. Upon restart the new address will be active, along with the new baud rate, if previously changed.

| Address S |  |  |  |  |  |  | aud Rate S |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADDRESS Switch Position |  |  |  |  |  |  | DIP Switch Position |  |  |
| Node Address | SW 1 | SW 2 | SW 3 | SW 4 | SW 5 | SW 6 | DeviceNet <br> Baud Rate | SW 7 | SW 8 |
|  | Switch Position Values |  |  |  |  |  | 125k | OFF | OFF |
|  | 32 | 16 | 8 | 4 | 2 | 1 | 250k | OFF | ON |
| 0 | OFF | OFF | OFF | OFF | OFF | OFF | 500k | ON | OFF |
| 1 | OFF | OFF | OFF | OFF | OFF | ON | Autobaud | ON | ON |
| 2 | OFF | OFF | OFF | OFF | ON | OFF |  |  |  |
| 3 | OFF | OFF | OFF | OFF | ON | ON |  |  |  |
| 4 | OFF | OFF | OFF | ON | OFF | OFF |  |  |  |
| 5 | OFF | OFF | OFF | ON | OFF | ON |  |  |  |
| ... |  |  |  |  |  |  |  |  |  |
| 62 | ON | ON | ON | ON | ON | OFF |  |  |  |
| 63 | ON | ON | ON | ON | ON | ON |  |  |  |

## How to Read Discrete Input Data - DeviceNet

1. Plug the DeviceNet connector into the device. This powers the unit electronics.
2. Allocate a Poll Connection to the device from the client.
3. Perform a poll command to the device from the client. The device returns 2 bytes of data using Assembly Instance 1 (default).
4. The discrete input channel values will be available in the first 2 bits of data in the $1^{\text {st }}$ byte returned. The bits are defined as:

Table 1 - Poll Response (Input Data) Assembly Instance 1

| Bit Positions |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Byte | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| $\mathbf{1}$ | Reset <br> Switch State | Auxiliary <br> Input State | Calibrate Close <br> Switch State | Calibrate Open <br> Switch State | Close <br> Output State | Open <br> Output State | Close Limit <br> Switch State | Open Limit <br> Switch State |
| $\mathbf{2}$ | 0 | 0 | 0 | 0 | 0 | Cycle Count <br> Alarm | Close <br> Timeout | Open <br> Timeout |

Table 2 - Poll Response (Input Data) Assembly Instance 2

| Bit Positions |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Byte | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |  |
| $\mathbf{1}$ | Reset <br> Switch State | Auxiliary Input <br> State | Calibrate Close <br> Switch State | Calibrate Open <br> Switch State | Close <br> Output State | Close <br> Output State | Close Limit <br> Switch State | Open Limit <br> Switch State |  |
| $\mathbf{2}$ | Analog Input <br> Overcurrent | Analog Input <br> Undercurrent | 0 | 0 | Analog <br> Input Alarm | Cycle Count <br> Alarm | Close Timeout <br> Alarm | Open Timeout <br> Alarm |  |
| $\mathbf{3}$ | Analog Input LSB (bits 0-7) |  |  |  |  |  |  |  |  |
| $\mathbf{4}$ | 0 | 0 | 0 | 0 | 0 | 0 | Analog Input MSB |  |  |

## EMERSON

Bus Options DM/DN: DeviceNet Protocol (continued)
Using Assembly instance 3 (Parameter 10), the cycle open and closetimes are added on to the poll bytes as shown below:
Table 3 - Poll Response Assembly Instance 3

| Byte | Description |
| :---: | :---: |
| 1 | Input Status Bits |
| 2 | Alarm Bits |
| 3 | AI LSB |
| 4 | AI MSB |
| 5 | LS Byte of Last Open Time |
| 6 | MS Byte of Last Open Time |
| 7 | LS Byte of Last Close Time |
| 8 | MS Byte of Last Close Time |

Using Assembly instance 4, the cycle count is added on to the poll bytes as shown below:
Table 4 - Poll Response Assembly Instance 4

| Byte | Description |
| :---: | :---: |
| 1 | Input Status Bits |
| 2 | Alarm Bits |
| 3 | AI LSB |
| 4 | AI MSB |
| 5 | LS Byte of Last Cycle Count |
| 6 | MLS Byte of Last Cycle Count |
| 7 | MMS Byte of Last Cycle Count |
| 8 | MS Byte of Last Cycle Count |

Assembly instance 5 incorporates all data, as shown:
Table 5 - Poll Response Assembly Instance 5

| Byte | Description |
| :---: | :---: |
| 1 | Input Status Bits |
| 2 | Alarm Bits |
| 3 | AI LSB |
| 4 | AI MSB |
| 5 | LS Byte of Last Open Time |
| 6 | MS Byte of Last Open Time |
| 7 | LS Byte of Last Close Time |
| 8 | MS Byte of Last Close Time |
| 9 | LS Byte of Last Cycle Count |
| 10 | MLS Byte of Last Cycle Count |
| 11 | MMS Byte of Last Cycle Count |
| 12 | MS Byte of Last Cycle Count |

## Bus Options DM/DN: DeviceNet Protocol-How to Energize and De-energize ValveSolenoids

1. Reconnect the device and allocate a Poll Connection to the device from the client.
2. Issue a Poll command from the client with a data value of 00,01 , or 02 . Each of the two possible outputs will be turned ON or OFF, as defined by a corresponding bit value of 1 or 0 . Note that having both open and close bit set is an illegal state and will be ignored by the controller.

Table 6 - Poll Request (Output Data)

| Bit Positions |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Byte | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ |  |
| $\mathbf{1}$ | 0 | 0 | 0 | Reset Cycle Count | Enable Cal Mode | Reset Alarms | Output 2 | 0 |

Setting the Reset Alarms bit to 1 clears the Open and Close Time counters and resets all active alarm notification bits. As long as this bit is set, the alarms will be inactive. The Enable Cal Mode bit is set to 1 to allow calibration of the limit switches sense positions. When the device is commanded into Cal Mode, normal operation of the outputs is disabled. The Closed and Open limit switches can then set active, which will cause the associated input LEDs to be activated, along with activating the corresponding Input 1 or Input 2 status bits.

The Reset Cycle Count bit is set to 1 to clear the cycle counter.

## EMERSON

Bus Options DM/DN: DeviceNetProtocol (continued)

## Parameters

The TopWorx ${ }^{T M}$ device is software-configured for several parameters. Table 7 defines the legal values and the default values for the I/O configuration selections available.

Table 7 - Configuration Parameters (Class 15)

| Instance | Parameter Name | Values | Default <br> Setting | Default <br> Value | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Max Open Time | 0 to 65535 <br> $(0-655.35$ <br> sec. $)$ | Disabled | 0 | Maximum allowed time for valve to open before triggering alarm (in 10's of milliseconds) |
| 2 | Max Close Time | 0 to 65535 <br> $(0-655.35$ <br> sec. $)$ | Disabled | 0 | Maximum allowed time for valve to close before triggering alarm (in 10's of milliseconds) |

## Definitions of these Parameters are as follows:

1. Max Open Time: Maximum allowed time in 10's of milliseconds for valve to open before triggering alarm.
2. Max Close Time: Maximum allowed time in 10 's of milliseconds for valve to close before triggering alarm.
3. Cycle Count Limit: Maximum number of valve cycles before triggering alarm.
4. *Analog High Limit: Highest analog value before triggering alarm.
5. *Analog Low Limit: Lowest analog value before triggering alarm.
6. Output Fault Action: Selection to determine whether each output will hold its last state or assume the value identified in the next parameter upon a device fault.
7. Output Fault Value: The value each output will assume after a Fault if Fault Value is selected above (hold last state is not selected).
8. Output Idle Action: Selection to determine whether each output will hold its last state or assume the value identified in the next parameter if an Idle Command is issued by the Master.
9. Output Idle Value: The value each output will assume upon an Idle Command if Idle Value is selected above (hold last state is not selected).
10. Assembly Configuration: This determines what data is returned in the poll response.

## EMERSON

Bus Option PM: Profibus Protocol with Mechanical SPDT Switches

## Wiring Diagram:



Bus Option PB: Profibus Protocol with Reed Switches
Wiring Diagram:



Bus Options PM/PB: Profibus Protocol (continued)

| Type of Network | Device Bus |
| :---: | :---: |
| Physical Media | Twisted pair, fiber |
| Network Topology | Bus, Ring, Star |
| Maximum Devices | max. 126 stations on one bus (maximum of 244 bytes input and output data possible for each slave) |
| Maximum Distance |  |
| DP | 93.75 Kbps and less-1200 meters $500 \mathrm{Kbps}-400$ meters 1.5 Mbps 200 meters 12Mbps - 100 |
| Maximum Distance with repeaters (max. of 9 repeaters can be used) | 9,500 meters with repeaters |
| Communication Methods | Per-to-peer, multicast or cyclic master-slave (uses token passing sequence) |
| Primary Usage | Used for Discrete and Analog for PLC, Variable Speed Drives, Remote I/O communications |
| Power \& Communications | Power is supplied separately from communications bus (can be supplied on a parallel power bus) |
| Device Power Supply | Devices are powered separately from communications bus.A 5A fuse must be placed in series with the input power terminals. |
| Wiring Types | Shielded twisted pair\#22 AWG |
| Device Addressing | Handheld/Software only |
| Governing Body | PROFIBUS International (PI) |
| Website | www.profibus.com |
| Electromagnetic Compatibility | EN 61326-1:2006, EN61000-4-2:1995inc. A2:2001,EN61000-4-3:2002, EN61000-4-4:2004 inc. A1:2010, EN 61000-4-6:2009, EN61000-4-8:1993inc. A1:2001, EN 55011:2009 inc. <br> A1:2010 |

NOTE: In order to meet EMC requirements, the Profibus communication cabling must be encased by conduit and properly grounded to the device housing.

Technical Data

| Power Requirements |  |
| :--- | :--- |
| PROFIDP 4I20 | 24 VDC $+-10 \%$ <br> Max I $=350 \mathrm{~mA}$ <br> maxi- mum <br> (solenoids/activated) |


| Profibus Info |  |
| :--- | :--- |
| ID | 09ED HEX |
| GSD file | TWIS09ED.GSD |
| Transmission Speed | 12Mbaud (max) |


| Line Parameters | Line Type A | Line Type B |
| :--- | :---: | :---: |
| Impedance | 135 to 165 | 100 to 130 |
| Capacitance per unit length | $<30$ | $<60$ |
|  |  |  |
| Loop resistance (V/km) | 110 | -- |


| Recommended Line Lengths |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transmission rate (kBaud) | 9.6 | 19.2 | 93.75 | 187.5 | 500 | 1200 | 1500 |
| Line Type A | 1200 | 1200 | 1200 | 1000 | 400 | 200 | 100 |
| Line Type B | 1200 | 1200 | 1200 | 600 | 200 | - | - |

## Software Parameters

| Output Byte |  | Fail Closed | Fail Open | Dual Coil |
| :---: | :---: | :---: | :---: | :---: |
| Bits |  |  |  |  |
| 7 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 6 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 5 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 4 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 3 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 2 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 1 | Output2 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ | High Closed |
| 0 | Output 1 | High Open | High Closed | High Open |
|  |  | Low Closed | Low Open |  |


| Input Byte 1 |  |  |
| :---: | :---: | :---: |
| Bits |  |  |
| 7 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 6 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 5 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 4 | $\mathrm{n} / \mathrm{a}$ | $\mathrm{n} / \mathrm{a}$ |
| 3 | SPARE | Input 4 |
| 2 | SPARE | Input 3 |
| 1 | High Closed | Input 2 |
| 0 | High Open | Input 1 |


| Diagnostic <br> Byte 1 |  |
| :---: | :---: |
| Bits |  |
| 7 | $\mathrm{n} / \mathrm{a}$ |
| 6 | $\mathrm{n} / \mathrm{a}$ |
| 5 | $\mathrm{n} / \mathrm{a}$ |
| 4 | $\mathrm{n} / \mathrm{a}$ |
| 3 | $\mathrm{n} / \mathrm{a}$ |
| 2 | Hard Wired high |
| 1 | Hard Wired high |
| 0 | Hard Wired high |

## 4-20mA Transmitter:Options EX/KX/MX/TX

## Wiring Diagrams:



| ELECTRICAL DATA |  |
| :--- | :--- |
| Voltage Input Range | $8.5-34$ Volts DC |
| Standard Output Signal | Two wire 4-20mA with out of range indication |
| Input Polarity | Bi-Directional |
| Primary Usage | The 2-wire 4-20mA transmitter will generate a nominal 4-20mA <br> output for full-range actuation of the valve. The <br> device will generate signals above 20mA and below 4mA to indicate <br> out of range rotation. |
| Rotation | The factory setting is 180 degree maximum for counterclockwise <br> rotation and 90 degree maximumfor counterclockwise rotation. <br> Minimum rotation is 20 degrees in either direction. Contact customer <br> service for rotations above factory settings. |
| Modes | Optional linearand rotary modes |
| Linearity | $+/-1 \%^{*}$ |
| Repeatability | $0.3 \%^{*}$ |
| Hysteresis | $0.5 \%^{*}$ |
| Temperature | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Electromagnetic Compatibility | EN 61326-1:2006, EN61000-4-2:1995inc. A1:1998 \& A2:2001, <br> EN61000-4-3:2002, EN 61000-4-4:2004, EN <br> $61000-4-5: 1995 ~ i n c . ~ A 1: 2001, ~ E N ~ 61000-4-6: 2009, ~ E N ~$ <br> $55011: 2009 ~ i n c . ~ A 1: 2010 ~$ |
| *Indicated linearity, repeatability and hysteresis is for the device only. Installed specifications will depend on the total |  |
| mechanical and electrical system's capability. |  |

## 4-20mA Transmitter: Protocol(continued)



## Operation of the 4-20mACurrent Position Transmitter

During run mode, the $4-20 \mathrm{~mA}$ position transmitter will output $4-20 \mathrm{~mA}$ for valve positions between and including the set points. In rotary mode, the module has an optional over or under travel correction if the valve position exceeds the high or low set point by $+/-3 \%$. In other words, the output will be 4 mA for travel within $3 \%$ under the low-end set point and 20 mA for travel within $3 \%$ over the high-end set point. If the travel exceeds this $3 \%$ over/undershot, the actual value will be output. The other user-selectable option is to calibrate the device without the over and under travel capability (Linear Mode). See the calibration flowchart in the document for additional information.

## EMERSON

## 4-20mA Transmitter: Protocol (continued)

Troubleshooting
Error Code and problem Shooting

| Problem | Probable Cause/Solution |
| :---: | :---: |
| Transmitter Module has no current output | If the LED on the Transmitter Module is not lit <br> - Loose or shorted signal connection (fix connection) <br> - Controller Board not responding (Replace Transmitter Module) <br> If the LED on the Circuit Board is lit <br> - Potentiometer is disengaged from shaft (must be returned for repair) <br> - Defective controller board (Replace Transmitter Module) |
| Transmitter does not output 4 or $20 \mathrm{~mA}(+/-$ $1 \%$ ) at desired end of travel | - Unit not calibrated (calibrate) <br> - Unit is calibrated (recalibrate - if still fails, replace board) |
| Output is not linear or does not track valve position or rotation | Input signal is not linear <br> - Linkage or drive mechanism is introducing non-linearity <br> - Unit is not calibrated (calibrate) |
| Error Code 4-3 | Start position is too low or in the dead-band position. |
| $\begin{array}{\|l} \hline \text { Error Code 4-4 } \\ \text { Error Code 4-5 } \end{array}$ | Start position is too high <br> Start and stop positions are less than $20^{\circ}$, increase valve rotation between start and stop positions to greater than $320^{\circ}$. |
| Error Code 4-6 | Rotation has exceeded $320^{\circ}$ limit. Decrease valve rotation between start and stop positions to less than $320^{\circ}$. |
| Error Code 4-7 | Calibration rotation was in the wrong direction or the potentiometer passed through the dead-band position. |
| Error Code 4-1 | Internal error has occurred. Recalibrate, if error continues, replace module. |

LED Flash Code Diagram
Flash Codes

| (first count - second count) | Interpretations |
| :---: | :--- |
| $0-0$ | Calibrated |
| $3-1$ | Counter-Clockwise Calibration, Waiting to calibrate the 4mA position, Rotary Mode |
| $3-2$ | Clockwise Calibration, Waiting to calibrate the 4mA position, Rotary Mode |
| $3-3$ | Waiting for 20mA Full Open Setting Button Press |
| $4-1$ | Calibration Required |
| $4-3$ | Calibration Start Value is Too Low |
| $4-4$ | Calibration Start Value is Too High |
| $4-5$ | End Value is Too Close to Start Value |
| $4-6$ | Maximum Rotation Exceeded |
| $4-7$ | Wrong Direction of Rotation |
| $5-1$ | Counter-Clockwise Calibration, Waiting to calibrate the 4mA position, Linear Mode |
| $5-2$ | Clockwise Calibration, Waiting to calibrate the 4mA position, Linear Mode |

During calibration, make sure the potentiometer is not rotating through its deadband area. The red dot located on the potentiometer should not rotate through the area marked with red during the full rotation of the valve. If it does, reposition the shaft.


EMERSON

## Integrated Pneumatic Pilots

## All 15mm Pilot Valves feature:

- Heat-resistant bobbin molded with $30 \%$ glass-filled polyester (PBT)
- Class $\mathrm{H} 200^{\circ} \mathrm{C}$ copper wire according to IEC $317-8$
- Encapsulation with specially designed, high-quality, glass-filled polyamide (PA66)
- Stainless steel guiding tube
- Plunger and core made of magnetic stainless steel specially designed for solenoid applications

Contact factory for technical pilot valve information.

## Pneumatic Hookup Procedures

Prior to connecting the supply air to the spool valve, flush the system to remove any debris or contaminates. Galvanized pipe can easily flake and contaminate the system and therefore is not recommended. A 40-micron point of use filter at every device is recommended.

## 2-Way Spool Valves

The TopWorx ${ }^{\text {TM }}$ spool valve is a 5 port, 2-way valve driven by an internally mounted pilot valve. The spool valve supply port and work ports ar e marked as follows:



| Spool Valve Specifications |  |
| :--- | :--- |
| Medium | Dried, filtered air (40-micron) |
| Max Operating <br> Pressure | 100 psi (0.7 MPa) (6.89Bar) |
| Min. Operating <br> Pressure | 30 psi (0.28 MPa) (2.76Bar) |
| Ambient Temperature <br> Range | Refer to Product Nameplate Marking |
| Flow Coefficient | 1.0 Cv |
| Environment Rating | Type 4, 4X, IP67 |
| Port Size | $1 / 4 "$ NPT or BSP for 1.0CV valve Exhaust <br> ports are 1/8" NPT or BSP |
| Valve Body | Available in Hardcoat Anodized <br> Aluminum or 316 Stainless Steel |
| Valve Seals | Buna-N/EPDM |

## Highly Recommended

TopWorx ${ }^{\text {TM }}$ highly recommends Locktite 567 brand thread sealant. Do not use a hard setting pipe compound. If Teflon thread seal tape is used, start the wrap on the second thread from the leading thread of the fitting. This will prevent tape shreds from contaminating the spool valve seals.

Breathers (AL-M30) should be installed in the exhaust ports, when NPT threads are specified, to keep debris from falling into the spool valve and damaging the seals. This must be addressed prior to installation, or storage.

A flow control may be used in Port 3, but should NEVER BE USED in Port 5. Any blockage or restriction may cause an internal pressure build-up inside the enclosure and pose a safety issue.

## Maintenance

No maintenance is required. Bearing's internal diameter should be checked after 1 million cycles for wear. Required dimension should be between 10.00 to 10.05 mm . Switch setting can be checked periodically.

Aggressive substances: e.g. acidic liquids or gases that may attack metals or solvents that may affect polymeric materials. If the equipment is likely to encounter aggressive substances, then it is the responsibility of the user to take suitable precautions that prevent it from being adversely affected, thus ensuring that the type of protection provided by the equipment is not compromised.

Suitable precautions: e.g. regular checks as part of routine inspections or establishing from the material's datasheets that it is resistant to specific chemicals. If in doubt, contact TopWorx ${ }^{\text {TM }}$ for assistance.

## Area Classifications

Intrinsically Safe Protection Method: Intrinsically safe units are designed to operate on very low current. A current limiting barrier is required for safe operation. For detailed requirements and installation information, refer to the control drawing listed on the product nameplate.

Non-Incendive Protection Method: Non-incendive units are designed with circuitry in which any arc or thermal effect produced, under intended operating conditions of the equipment, is not capable of igniting the flammable gas, vapor or dust-air mixtures.

General Purpose Protection Method: General purpose units are designed to be operated in areas free from flammable gas, vapor, or dust-air mixtures.

## Approvals \& Certifications

TopWorx ${ }^{\text {TM }}$ is proud to be certified for use in the following markets:

ATEX - European
Union

IEC - Europe and other World Areas, including Australia \& New Zealand

US \& Canada

Brazil

Russia

China PESO


TopWorx ${ }^{\text {TM }}$ products carry a wide range of certification markings:
Class I, Div 1 - Intrinsically Safe and Explosion-proof
Class I, Div 2 - Non-incendive
Class III - Dust Ignition Proof
Ex ia IIC - Zone0/Zone1 - Intrinsically Safe
Ex d IIC \& IIB +H 2 - Zone1 - Flameproof
Ex nA nC IIC - Zone2 - Non-arcing/Non-sparking

Consult factory for copies of our certifications, which will include all product specifications, such as ambient temperature ranges, gas/dust group coverage, intrinsic safety parameters, and special conditions for safe use.

## Safe Use - Special Conditions of Safe Use (All installations)

## For Intrinsically Safe applications:

- The 4-20mA loop circuit and the various additional sub-assemblies (switches, sensors, valves, etc.) shall be treated as separate intrinsically safe circuits.
- The entity parameters for simple switches that are not covered by a certificate are $\mathrm{Ui}=30 \mathrm{~V}, \mathrm{li}=200 \mathrm{~mA}$ and $\mathrm{Pi}=0.72 \mathrm{~W} / \mathrm{switch}$ ( T 4 ) or $\mathrm{Pi}=0.34 \mathrm{~W} / \mathrm{switch}$ ( T 6 ). The entity parameters of certified devices fitted shall be obtained from the applicable certificate.


## For Increased Safety applications:

- The enclosure has the following limiting temperatures: $-50^{\circ} \mathrm{C}$ to $+180^{\circ} \mathrm{C}$ for Silicone O -rings.

For Increased Safety and Non-Incendive applications:

- When fitted with an indicator dome, the non-metallic parts incorporated in the enclosure of this equipment may generate an ignition- capable level of electrostatic discharge. Therefore, the equipment shall only be cleaned with a damp cloth.


## Consult Factory for Recommended Operating Temperature

## PRODUCT SUPPORT INFORMATION

Please contact factory or Global Support Offices for additional technical information and support on TopWorx ${ }^{\text {TM }}$ ESD Re-Design with GOTM product.

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